

Amendment to Claims

CLAIMS

What is claimed is:

1. (Currently amended) ~~A video camera with an imaging system and a sequential diversity processor for~~ enhanced image clarification comprising:

an imaging system with an adaptive optic device arranged for canceling aberrations introduced by the optical medium to produce solely adapted in-focus digital images of the object; and

a sequential diversity processor using said digital images as diverse images and using changes in said adaptive optic device as diversities to calculate control signals for said adaptive optic device.

~~an imaging system for producing a sequence of digital images of an object, said object being continuously distorted by a changing optical medium;~~

~~an adaptive optic device located within said imaging system, controlled by said sequential diversity processor and arranged for canceling aberrations introduced by said medium, aberrations such as those caused by a turbulent atmosphere or unwanted changes in said imaging system, to thereby provide solely adapted in-focus images of said object;~~

~~a detector array within said imaging system arranged for receiving said solely adapted in-focus images and producing digital image representations thereof; and~~

~~a sequential diversity processor connecting with said detector array and said adaptive optic device, said sequential diversity processor receiving said digital image representations from said detector array and providing sequential control signals to~~

~~said adaptive optic device to enable said adaptive optic device to cancel said aberrations.~~

2. (Currently amended) The camera of claim 1 wherein said sequential diversity processor utilizes diversity $D(k-1)$, the diversity at time $k-1$, along with current and previous digital images, $I(k)$ and $I(k-1)$, as diverse images to produce $Q(k-1)$, an estimate of the residual aberrations in said solely adapted in-focus image of said object at time $k-1$ ~~and~~ ; wherein said sequential diversity processor sets diversity $D(k)$ to the negative of that estimate, that is, $D(k) = -Q(k-1)$; and wherein $T(k-1)$, the signal produced by the sequential diversity processor to control the adaptive optic device at time $k-1$, is added to $D(k)$, to produce a control signal at time k , that is, $T(k) = T(k-1) + D(k)$, which also implies that $D(k) = T(k) - T(k-1)$.

3. and 4. (Cancelled)